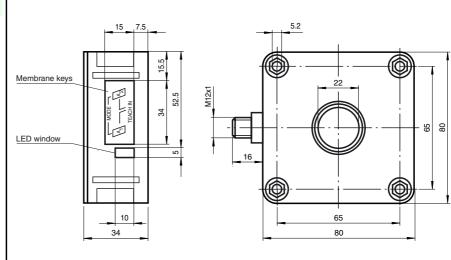
### Ultrasonic sensor UB2000-F42-E5-V15

### **Dimensions**





### Features

#### Switch output

- · Extremely small unusable area
- TEACH-IN
- Interference suppression (adjustable width of sound cone in close range)
- Temperature compensation
- · Synchronisation options

Electrical connection

+ U<sub>B</sub>

Sync

- U

Switch output

– n.c.

Standard symbol/Connections:

1 (BN)

2 (WH)

<u>5</u> (GY)

4 (BK)

(BU)

Core colours in accordance with EN 60947-5-2.

(version E5, pnp)

U

⊅

NO/NC selectable

### **Technical data**

General specifications Sensing range Adjustment range 60 ... 2000 mm 90 ... 2000 mm Unusable area 0 ... 60 mm Standard target plate 100 mm x 100 mm Transducer frequency approx, 175 kHz Response delay approx. 150 ms Indicators/operating means LED green LED yellow LED red **Electrical specifications** Operating voltage No-load supply current I<sub>0</sub>  $\leq$  50 mA Input/Output bi-directional Synchronisation 0 level -U<sub>B</sub>...+1 V 1 level: +4 V...+UB Synchronisation frequency Common mode operation < 30 HzMultiplex operation Output Output type Repeat accuracy Rated operational current le Voltage drop U<sub>d</sub> < 2.5 V Switching frequency f ≤ 3 Hz Range hysteresis H Temperature influence ± 1 % of full-scale value Standard conformity Standards EN 60947-5-2 Ambient conditions Ambient temperature Storage temperature -40 ... 85 °C (233 ... 358 K) Mechanical specifications Protection degree IP54 Connection connector V15 (M12 x 1), 5 pin Material PBT Housing Transducer 140 g Mass

permanently green: Power on permanent: switching state switch output flashing: TEACH-IN function normal operation: "fault" TEACH-IN function: no object detected

10 ... 30 V DC , ripple 10 %<sub>SS</sub>

input impedance: > 12 KOhm synchronisation pulse:  $\ge$  100  $\mu$ s, synchronisation interpulse period:  $\ge$  2 ms

CE

 $\leq$  30/n Hz, n = number of sensors

1 switch output E5, pnp NO/NC, parameterisable  $\leq 0.5~$  % of switching point 200 mA , short-circuit/overload protected 1 % of the set operating distance

-25 ... 70 °C (248 ... 343 K)

epoxy resin/hollow glass sphere mixture; foam polyurethane, cover PBT

# 111705\_ENG.xml

2005-07-27



Printed in Germany

### Parameterisation:

You can use 2 keys to parameterise the sensor. In order to start the switch point 1 learning mode, press the A1 key; in order to start the switch point 2 learning mode, press the A1 key.

If you keep both keys pressed as you switch on the power supply, the sensor will switch over to the sensitivity adjustment mode of operation.

In case the parameterisation procedure is not completed within 5 minutes, the sensor will discontinue the process and retain all previous settings.

### Teaching in switch points:

Teaching in A1 switch point by pressing A1 key.

Keep A1 key pressed for > 2 s	The sensor enters the switch point 1 learning mode
Position target object in the desired distance	The sensor indicates via LED lights whether the target object has been detected. In case the object has been detected, the yellow LED will flash; if the object has not been detected, the red LED flashes.
Briefly press the A1 key	The sensor completes the switch point 1 TEACH-IN process and saves this value in non- volatile memory. In the event of an uncertain object (flashing red LED), the value learned is

Analogously, the A2 switch point is learned in the same fashion as described above using the A2 key.

invalid. The system exits the TEACH-IN mode.

### Switching hysteresis operation mode <--> switch point/window operation mode:

Keep both A1 and A2 keys pressed	The sensor indicates the current operation mode through the green LED. permanent green: Switch point/window operation mode flashing green: Hysteresis operation mode
after 2 seconds:	The sensor changes the operation mode which can be identified through the green LED. permanent green: Switch point/window operation mode flashing green: Hysteresis operation mode
Release keys	The green LED of the sensor keeps indicating the operation mode selected for additional 5 seconds

### Suppression of disturbing targets

Some types of installation or particular conditions during operation of an ultrasonic sensor may admit that undesired objects (such as shelf brow posts, edges of machines) are closer than the actual target as they enter the recording range. In this case, the sensor would normally detect these objects rather than the desired target. So in order to ensure an error-free operation, in may be necessary to suppress those objects.

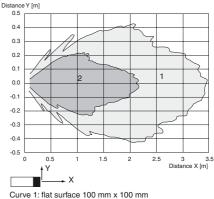
Objects can be suppressed if they meet the following conditions:

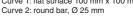
### Model number

### UB2000-F42-E5-V15

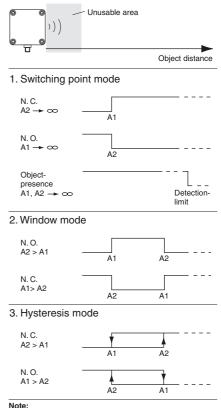
## Characteristic curves/additional information

### Characteristic response curve





### Programmable operation modes



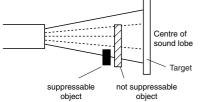
→ ∞ means: cover transducer surface with your hand, while teaching the switching point.

If A1 = A2, the output works like A2 > A1

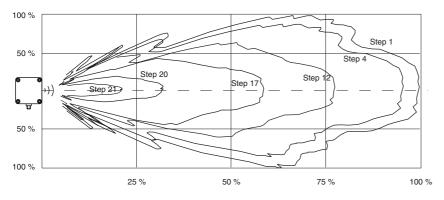
### Ultrasonic sensor

- The disturbing target must not hide the actual target completely.
- The amplitude of the disturbing signal must be smaller than the amplitude of the desired signal.
- The disturbing target must remain in the edge region of the sound lobe and must not enter its center.

### Sound lobe



The suppression of the disturbing target is effected through reduction of the response sensitivity. This figure shows its effect on the response characteristics of the sensor. The sensor is preset on step 1 by the manufacturer.



### Sensitivity adjustment for suppression of disturbing targets

Remove the actual target object from the detection range.

Keep A1 and A2 keys pressed as you switch on power supply	The sensor enters the sensitivity adjustment mode of operation. The sensor sensitivity can be adjusted in 24 steps. Step 1 = high response Step 24 = low response
Briefly press the A1 key	Response is increased. The LED lights indicate the actual state of the sensor. - flashing red: no disturbing target detected - flashing yellow: disturbing target detected - permanent red: upper setting limit is reached.
Briefly press the A2 key	Response is decreased. The LED lights indicate the actual state of the sensor. - flashing red: no disturbing target detected - flashing yellow: disturbing target detected - permanent red: lower setting limit is reached.
Press both A1 and A2 keys at once	Exiting sensitivity adjustment. The sensor response is saved in non-volatile memory. In the event the sensitivity adjustment is not exited through this procedure, the sensor will exit this operation mode automatically after 5 minutes, and the previous sensitivity value remains valid.

### Synchronisation

In order to prevent conflicts, the sensor is equipped with a synchronisation connection. In case this is unwired, the sensor function is based on an intern clock rate. Several sensors can be synchronised through the following methods:

### External synchronisation:

The sensor can be synchronised by application of external square wave voltage. A synchronising pulse at the synchronisation input triggers a measuring cycle. The pulse width needs to be bigger than 100 µs. The measuring cycle is started with the falling edge. A low level > 1 s or an open synchronisation input causes the sensor to operate at normal operating mode. A high level at the synchronisation input deactivates the sensor.

There are two possible operation modes:

### Ultrasonic sensor

### UB2000-F42-E5-V15

- Several sensors are controlled by the same synchronisation signal. The sensors function in common mode.

- The respective synchronising pulses are directed to just one sensor each cyclically. The sensors function in multiplex mode.

Self synchronisation:

The synchronisation connections of up to 5 sensors offering a self synchronisation option are interconnected. After switching on power supply, these sensors function in the multiplex mode. The response delay increases according to the number of sensors to be synchronised. During the TEACH-IN process no synchronisation can be performed and vice versa. For teaching in switch points, the sensors need to be operated in an unsynchronised state.

### Note:

If the option for synchronisation is not used, the synchronisation input has to be connected to ground (0 V) or the sensor has to be operated via a V1 cable connector (4-pin).

### Accessories

Mounting aids MH 04-3505 **MHW 11** 

Cable sockets \*) V15-G-2M-PVC V15-W-2M-PUR

\*) For additional cable sockets see section "Accessories".